



We design and supply hydraulically actuated tools for construction tasks subsea. The tool shown to the left was designed to be manipulator deployed and remove structural pins in case of an emergency. Keeping in line with our tooling philosophy, the tool is hydraulically energized through a dual-port hotstab. If the tool becomes unusable during

operations, the ROV can easily disconnect from the tool without losing vital system hydraulic fluid.

All of our ram driven tools have integral load holding, relief and flow control built into the tooling package. This allows any number of end-users to utilize our tools without requiring extra equipment. If you have any questions about our ROV construction tooling, please contact the Technical Department.

Specifications

Actuation Pressure Ranges	Variable, 1,000 – 2,000 psi
Actuation Forces	Variable, per customer specs
Fluid Interface	API 17D or ISO (API 17H)
Reaction Interface	Developed with customer
Depth Ratings	Full ocean depth
Ram Speed Ranges	Fully adjustable up to the ROV's maximum flow rate